

# A Combined Spectral-Finite Element Method for Solving Two-Dimensional Unsteady Navier–Stokes Equations

BEN-YU GUO AND WEI-MING CAO

*Shanghai University of Science and Technology, Shanghai, China*

Received January 4, 1989; revised April 24, 1991

---

In this paper, a combined Fourier spectral-finite element method is proposed for solving two-dimensional, semi-periodic, unsteady Navier–Stokes equations. The convergence is proved and the numerical results are presented. © 1992 Academic Press, Inc.

---

## I. INTRODUCTION

When we study boundary layer stability, unsteady separation of viscous fluid flow, flow past a suddenly heated vertical plate, and other fluid dynamics problems, we have to solve Navier–Stokes equations with semi-periodic boundary conditions. Many people have developed numerical methods to solve these problems. For instance, Murdock [1, 2], Ingham [3, 4], Beringen [5], Milinazo and Saffman [6], and Ben-yu Guo [7] used combined spectral-finite difference methods. It means that spectral methods are adopted in the periodic directions, while finite difference methods are used in the non-periodic directions. Recently, Canuto, Maday, and Quarteroni [8, 9], Ben-yu Guo and Wei-ming Cao [10], and others, studied the combined spectral (or pseudospectral)-finite element methods. Another useful method is to use combined Fourier–Chebyshev approximations [11–13]. In this method, Fourier approximations are used in the periodic directions, while Chebyshev approximations are used in the other directions.

In this paper, we generalize the work of [8–10] to construct a combined Fourier spectral-finite element scheme for solving two-dimensional, semi-periodic, unsteady Navier–Stokes equations. Surely such problems can also be solved by spectral-finite difference methods or combined Fourier–Chebyshev approximations. But it is difficult to extend them to three-dimensional problems with non-rectangular domains. On the contrary, the method in this paper can be generalized easily to more complicated problems.

In Section II, we construct the combined spectral-finite element scheme. In Section III, we state the convergence

theorem. The numerical results are presented in Section IV. They show that such a scheme gives much better performances than the usual finite element method does. We prove the convergence in the final two sections.

Some lemmas proved in this paper are also useful for other relevant problems.

## II. THE SCHEME

Let

$$I = \{x/0 < x < 1\}, \quad \tilde{I} = \{y/0 < y < 2\pi\}, \quad \Omega = I \times \tilde{I},$$

and  $U = (U^{(1)}, U^{(2)})$ ,  $P$ ,  $f$ , and  $\nu > 0$  be the velocity, the ratio of pressure over density, the body force, and the kinetic viscosity, respectively. We consider the two-dimensional unsteady Navier–Stokes equations as follows:

$$\begin{aligned} \frac{\partial U}{\partial t} + (U \cdot \nabla)U + \nabla P - \nu \nabla^2 U &= f, \\ \text{in } \Omega \times (0, T], \\ \nabla \cdot U &= 0, \quad \text{in } \Omega \times [0, T], \\ U|_{t=0} &= U_0, \quad \text{in } \Omega. \end{aligned} \tag{2.1}$$

Assume that  $U$ ,  $P$ , and  $f$  have the period  $2\pi$  for the variable  $y$ , and that

$$\begin{aligned} U(0, y, t) &= U(1, y, t) = 0, \\ \forall (y, t) &\in \tilde{I} \times [0, T]. \end{aligned}$$

In addition,  $P$  satisfies the following normalizing condition:

$$\iint_{\Omega} P(x, y, t) \, dx \, dy = 0, \quad \forall t \in [0, T].$$

For  $\mu \geq 0$ , we denote by  $H^\mu(\Omega)$ ,  $\|\cdot\|_\mu$  and  $|\cdot|_\mu$  the classical

Sobolev space, its norm, and semi-norm, respectively. In particular, we define  $\mathcal{L}^2(\Omega) = H^0(\Omega)$  with the norm  $\|\cdot\|$  and the inner product  $(\cdot, \cdot)$ . Furthermore, define

$$C_p^\infty(\Omega) = \{\eta \in C^\infty(\Omega) / \eta \text{ has the period } 2\pi \text{ for the variable } y\},$$

$$C_{0,p}^\infty(\Omega) = \{\eta \in C_p^\infty(\Omega) / \eta(0, y) = \eta(1, y) = 0, \forall y \in \tilde{I}\}.$$

$H_p^\mu(\Omega)$  and  $H_{0,p}^\mu(\Omega)$  denote the closures of  $C_p^\infty(\Omega)$  and  $C_{0,p}^\infty(\Omega)$  in  $H^\mu(\Omega)$ , respectively. We also define

$$\tilde{\mathcal{L}}^2(\Omega) = \left\{ \eta \in \mathcal{L}^2(\Omega) \left/ \int\int_\Omega \eta \, d\Omega = 0 \right. \right\}.$$

The generalized solution of (2.1) is the pair  $(U(t), P(t)) \in [H_{0,p}^1(\Omega)]^2 \times \tilde{\mathcal{L}}^2(\Omega)$  satisfying

$$\begin{aligned} & \frac{d}{dt}(U(t), v) + ((U(t) \cdot \nabla) U(t), v) \\ & \quad - b(v, P(t)) + \nu a(U(t), v) \\ & = (f(t), v), \quad \forall v \in [H_{0,p}^1(\Omega)]^2, \\ & b(U(t), \omega) = 0, \quad \forall \omega \in \tilde{\mathcal{L}}^2(\Omega), \\ & U(0) = U_0, \end{aligned} \tag{2.2}$$

where

$$\begin{aligned} a(\eta, \xi) &= \int\int_\Omega (\nabla \eta)(\nabla \xi) \, d\Omega, \\ b(\eta, \xi) &= \int\int_\Omega (\nabla \cdot \eta) \xi \, d\Omega. \end{aligned}$$

We introduce a trilinear form  $J(\cdot, \cdot, \cdot): [H^1(\Omega)]^2 \times R^1 \rightarrow R^1$  as follows:

$$J(\eta, \varphi, \xi) = \frac{1}{2} [(\varphi \cdot \nabla) \eta, \xi] - ((\varphi \cdot \nabla) \xi, \eta).$$

Clearly, we have

$$J(\eta, \varphi, \xi) + J(\xi, \varphi, \eta) = 0, \tag{2.3}$$

and if  $\nabla \cdot \varphi = 0$ , then

$$J(\eta, \varphi, \xi) = ((\varphi \cdot \nabla) \eta, \xi).$$

Thus (2.2) is equivalent to

$$\begin{aligned} & \frac{d}{dt}(U(t), v) + J(U(t), U(t), v) \\ & \quad - b(v, P(t)) + \nu a(U(t), v) \\ & = (f(t), v), \quad \forall v \in [H_{0,p}^1(\Omega)]^2, \\ & b(U(t), \omega) = 0, \quad \forall \omega \in \tilde{\mathcal{L}}^2(\Omega), \\ & U(0) = U_0. \end{aligned} \tag{2.4}$$

For numerical solution of (2.4), we approximate the first equation directly. While to tackle the incompressible constraint (i.e., the second equation of (2.4)), we adopt the idea of artificial compression (see Témam [14]), that is, to approximate the incompressible condition by the equation

$$\begin{aligned} & \beta \frac{d}{dt}(P(t), \omega) + b(U(t), \omega) = 0, \\ & \forall \omega \in \tilde{\mathcal{L}}^2(\Omega), \end{aligned}$$

where  $\beta > 0$  is a small parameter.

Now we construct the scheme. First, we divide  $I$  into  $M_h$  subintervals, with the nodes  $0 = x_0 < x_1 < \dots < x_{M_h} = 1$ . Let  $I_l = (x_{l-1}, x_l)$ ,  $h_l = x_l - x_{l-1}$ ,  $h = \max_{1 \leq l \leq M_h} h_l$ , and  $h' = \min_{1 \leq l \leq M_h} h_l$ . We assume, furthermore, that there exists a positive constant  $d$  independent of the divisions of  $I$ , such that  $h/h' \leq d$ . For any integer  $k \geq 0$ , we denote by  $P_k$  the set of all the polynomials defined on  $R^1$  of degree  $\leq k$ . We define the finite element subspaces in the non-periodic directions as

$$\begin{aligned} \tilde{S}_h^k &= \{\eta / \eta|_{I_l} \in P_k, 1 \leq l \leq M_h\}, \\ S_h^k &= \tilde{S}_h^k \cap H_0^1(I). \end{aligned}$$

Suppose  $N$  is a positive integer; we define the subspaces for Fourier spectral approximations as follows:

$$S_N = \text{Span}\{e^{ijv} / |j| \leq N\}.$$

Let  $\alpha = (N, h, k)$ , we define the following finite dimensional subspace as the trial function space for the velocity

$$X_\alpha = \{S_h^{k+1} \otimes S_N\} \times \{S_h^{k+2} \otimes S_N\}.$$

The trial function space for the pressure  $P$  is

$$Y_\alpha = \{S_h^k \otimes S_N\} \cap \tilde{\mathcal{L}}^2(\Omega).$$

Let  $P_N$  be the orthogonal projection from  $\mathcal{L}^2(\tilde{I})$  onto  $S_N$ .

$\Pi_h^k$  is the piecewise Lagrange interpolation of order  $k$  from  $C(\bar{I})$  onto  $S_h^k$ ; i.e., for any  $\eta \in C(\bar{I})$ ,  $\Pi_h^k \eta \in S_h^k$  satisfies

$$\begin{aligned} (\Pi_h^k \eta) \left( x_{l-1} + \frac{m}{k} h_l \right) &= \eta \left( x_{l-1} + \frac{m}{k} h_l \right), \\ 0 \leq m \leq k, 1 \leq l \leq M_h. \end{aligned}$$

We obviously have that

$$P_N \circ \Pi_h^k = \Pi_h^k \circ P_N.$$

Let  $\tau$  be the mesh size in time  $t$  and  $S_\tau = \{t = l\tau / 0 \leq l \leq [T/\tau]\}$ . Define

$$\eta_i(t) = \frac{1}{\tau} (\eta(t + \tau) - \eta(t)).$$

A fully discrete spectral-finite element scheme for (2.4) is to find the pair  $(u(t), p(t)) \in X_\alpha \times Y_\alpha$  for all  $t \in S_\tau$ , such that

$$\begin{aligned} (u_i(t), v) + J(u(t) + \delta\tau u_i(t), u(t), v) \\ - b(v, p(t) + \theta\tau p_i(t)) \\ + \nu a(u(t) + \sigma\tau u_i(t), v) \\ = (P_N \circ \Pi_h^k f(t), v), \quad \forall v \in X_\alpha, \quad (2.5) \\ \beta(p_i(t), \omega) + b(u(t) + \theta\tau u_i(t), \omega) \\ = 0, \quad \forall \omega \in Y_\alpha, \\ u(0) = P_N \circ \Pi_h^{k+1} U_0, \quad p(0) = 0, \end{aligned}$$

where  $\delta, \sigma \geq 0$  and  $\theta > \frac{1}{2}$  are parameters.

*Remark 1.* Let  $\varphi_\alpha$  be the  $L^2$ -projection operator from  $\tilde{\mathcal{L}}^2(\Omega)$  onto  $Y_\alpha$ . Then it follows from the second equation of (2.5) that

$$\begin{aligned} p(t + \tau) &= p(t) - \frac{\tau}{\beta} [\theta \varphi_\alpha(\nabla \cdot u(t + \tau)) \\ &+ (1 - \theta) \varphi_\alpha(\nabla \cdot u(t))]. \quad (2.6) \end{aligned}$$

By substituting the above formula into the first equation of (2.5), we obtain

$$\begin{aligned} (u(t + \tau), v) + \delta\tau J(u(t + \tau), u(t), v) \\ + \frac{\theta^2 \tau^2}{\beta} (\varphi_\alpha(\nabla \cdot u(t + \tau)), \varphi_\alpha(\nabla \cdot v)) \\ + \sigma\nu\tau a(u(t + \tau), v) \\ = R(t)(v), \quad \forall v \in X_\alpha, \quad (2.7) \end{aligned}$$

where  $R(t)$  is a linear form defined on  $X_\alpha$  and depends only

on  $u(t)$ ,  $p(t)$ , and  $f(t)$ . Clearly, if  $R(t) = 0$ , then by putting  $v = u(t + \tau)$  in (2.7), we have from (2.3) that

$$\begin{aligned} \|u(t + \tau)\|^2 + \frac{\theta^2 \tau^2}{\beta} \|\varphi_\alpha(\nabla \cdot u(t + \tau))\|^2 \\ + \sigma\nu\tau \|u(t + \tau)\|_1^2 = 0. \end{aligned}$$

Hence  $u(t + \tau) = 0$ . This implies that (2.7) has exactly one solution. As soon as  $u(t + \tau)$  is found, we can obtain  $p(t + \tau)$  by (2.6) immediately. In this way, we can solve the velocity and the pressure separately. This is, indeed, one of the advantages of the artificial compression treatment.

*Remark 2.* We observe from (2.7) that the artificial compression coefficient  $\beta$  is, in fact, a penalty parameter for restraint  $\nabla \cdot U = 0$ . Usually, a penalty method takes the term  $1/\varepsilon(\nabla \cdot U, \nabla \cdot v)$  ( $\varepsilon \rightarrow 0$ ) to be the penalty function. But its numerical result is not good. It is interesting that if we calculate the integrations in the penalty function by a rough quadrature rule instead of calculating them exactly, then the results become better [15, 16]. This method is called the selective reduced integration and penalty method (or RIP method). The projection operator  $\varphi_\alpha$  in the penalty function  $(\theta^2 \tau^2 / \beta)(\varphi_\alpha(\nabla \cdot u(t + \tau)), \varphi_\alpha(\nabla \cdot v))$  in (2.7) is just an expression of the idea of the RIP method.

### III. THE CONVERGENCE THEOREM

For describing the errors of the numerical solutions, we introduce the notation,

$$\begin{aligned} E(\eta, \xi, t) &= \|\eta(t)\|^2 + \beta \|\xi(t)\|^2 + \nu\tau(\sigma + \theta) \|\eta(t)\|_1^2 \\ &+ \tau \sum_{t' \leq t - \tau} \{r_0 \tau (\|\eta_{i'}(t')\|^2 \\ &+ \beta \|\xi_{i'}(t')\|^2) + \nu(1 - 6\varepsilon) \|\eta(t')\|_1^2\}, \end{aligned}$$

where  $\varepsilon > 0$  is a suitably small constant,  $r_0 \geq 0$ .

Suppose  $\mathcal{B}$  is a Banach space, and  $\mathcal{I} \subset \mathbb{R}^1$  is an interval. We define

$$\begin{aligned} \mathcal{L}^2(\mathcal{I}, \mathcal{B}) &= \left\{ \eta/\eta: \mathcal{I} \rightarrow \mathcal{B}, \right. \\ &\left. \|\eta\|_{\mathcal{L}^2(\mathcal{I}, \mathcal{B})} = \left( \int_{\mathcal{I}} \|\eta(t)\|_{\mathcal{B}}^2 dt \right)^{1/2} < \infty \right\}. \end{aligned}$$

Similarly, we define the spaces  $C(\mathcal{I}; \mathcal{B})$ , and  $H^\mu(\mathcal{I}; \mathcal{B})$ , etc.

For convenience, we recall the definition of non-isotropic Sobolev spaces as [17], for  $r \geq 0$ , and  $s \geq 0$ ,

$$H^{r,s}(\Omega) = \mathcal{L}^2(\bar{I}, H^r(I)) \cap H^s(\bar{I}, \mathcal{L}^2(I)).$$

equipped with the norm

$$\|\eta\|_{H^{r,s}(\Omega)} = (\|\eta\|_{\mathcal{L}^2(\tilde{\Gamma}, H^r(I))}^2 + \|\eta\|_{H^s(\tilde{\Gamma}, \mathcal{L}^2(I))}^2)^{1/2}.$$

If  $r \geq 1, s \geq 1$ , then we define

$$M^{r,s}(\Omega) = H^{r,s}(\Omega) \cap H^1(\tilde{\Gamma}, H^{r-1}(I)) \cap H^{s-1}(\tilde{\Gamma}, H^1(I)),$$

with the norm

$$\|\eta\|_{M^{r,s}(\Omega)} = (\|\eta\|_{H^{r,s}(\Omega)}^2 + \|\eta\|_{H^1(\tilde{\Gamma}, H^{r-1}(I))}^2 + \|\eta\|_{H^{s-1}(\tilde{\Gamma}, H^1(I))}^2)^{1/2}.$$

Besides, we denote by  $H_p^{r,s}(\Omega)$  the closure of  $C_p^\infty(\Omega)$  in  $H^{r,s}(\Omega)$ ,  $H_{0,p}^{r,s}(\Omega)$ , and  $M_{0,p}^{r,s}(\Omega)$  are the closures of  $C_{0,p}^\infty(\Omega)$  in  $H^{r,s}(\Omega)$  and  $M^{r,s}(\Omega)$ , respectively.

**THEOREM 1.** *Let  $(U, P)$  be the solution of (2.4) and  $(u, p)$  the solution of (2.5). Assume that  $U \in C(0, T; M_{0,p}^{r,s}(\Omega)) \cap H^1(0, T; H^1(\Omega) \cap H_p^{r-1,s-1}(\Omega)) \cap H^2(0, T; \mathcal{L}^2(\Omega))$ ,  $P \in C(0, T; H_p^{r-1,s-1}(\Omega) \cap H^1(0, T; \mathcal{L}^2(\Omega))$ ,  $f \in C(0, T; H_p^{r-1,s-1}(\Omega))$ , with  $r \geq 1, s \geq 1, \bar{r} = \min(r, k + 2)$ . Suppose  $\beta = O(\tau^2)$ ,  $h = O(N^{-\mu})$ , and  $\tau = O(N^{-\lambda})$  in (2.5),  $\mu \geq 1, \lambda > 0, h, N^{-1}$ , and  $\tau$  are sufficiently small. If either of the following two conditions is satisfied:*

- (i)  $\sigma > \frac{1}{2}, \theta > \sigma/(2\sigma - 1)$ , and  $\lambda > \max((1 + \mu)/3, 1 + 3\mu - 2\mu\bar{r}, 3 + \mu - 2s)$ ; (3.1)
- (ii)  $\sigma \leq \frac{1}{2}$  and  $\tau(C_d h^{-2} + N^2) < 2\theta - 1/(v(\sigma + \theta(1 - 2\sigma)))$ ;

then there exists a positive constant  $C^*$  depending only on  $U, P, f$ , and  $v$ , such that for all  $t \in S_\tau$ , we have

$$E(U - u, P - p, t) \leq C^*(\tau^2 + h^{2(r-1)} + N^{2(1-s)}).$$

**Remark 2.** If  $\delta = \theta > \frac{1}{2}$ , then condition (3.1) is not necessary.

**IV. NUMERICAL RESULTS**

In this section, we examine the numerical performances of the combined spectral-finite element scheme (2.5) by two

**TABLE I**  
Example (1),  $\tau = 10^{-2}, \beta = 10^{-3}, t = 5$

		N = 4		N = 8	
		$E^*(u^{(1)}, t)$	$E^*(u^{(2)}, t)$	$E^*(u^{(1)}, t)$	$E^*(u^{(2)}, t)$
Spectral-	$M_h = 5$	2.1379-3	9.8124-4	7.6151-4	8.2940-4
F.E.M.	$M_h = 10$	1.9619-3	6.0285-4	2.6212-4	3.5686-4
F.E.M.	$M_h = 5$	1.8724-2	1.0882-2	3.8954-3	2.4330-4
	$M_h = 10$	1.6047-2	9.0782-3	3.8383-3	2.2202-3

**TABLE II**

Example (2),  $\tau = 10^{-2}, \beta = 10^{-3}, t = 5$

		N = 4		N = 8	
		$E^*(u^{(1)}, t)$	$E^*(u^{(2)}, t)$	$E^*(u^{(1)}, t)$	$E^*(u^{(2)}, t)$
Spectral-	$M_h = 5$	1.8953-3	6.7098-4	8.9871-4	5.9659-4
F.E.M.	$M_h = 10$	1.7296-3	4.9014-4	5.0291-4	3.5346-4
F.E.M.	$M_h = 5$	1.4452-2	7.6244-3	4.6631-3	2.2337-3
	$M_h = 10$	1.4994-2	7.6532-3	5.7109-3	2.1279-3

examples. In each example, the velocity is determined separately by the stream function

- (1)  $\psi(x, y, t) = 0.1 \exp(x + \sin y + 0.1t)$ ,
- (2)  $\psi(x, y, t) = 0.1 \sin(x) \exp(\sin y + 0.1t)$ ,

while the pressure  $P$  is taken to be 0 constantly. Besides, we assume the kinetic viscosity  $\nu = 10^{-2}$ , and choose the body force  $f$  such that  $U, P$ , and  $f$  satisfy (2.4) exactly.

We consider only the case of  $k = 0$  in scheme (2.5); i.e., the finite element subspaces in the  $x$  direction for  $(u^{(1)}, u^{(2)})$  and  $p$  are piecewise linear, piecewise quadratic, and piecewise constant, respectively. For comparison, we also solve (2.4) by the finite element method, in which the domain  $\bar{\Omega}$  is divided into  $M_h(2N + 1)$  congruent small rectangles, each with the length  $h_x = 1/M_h$  and the width  $h_y = 2\pi/(2N + 1)$ . We take the trial space for  $(u^{(1)}, u^{(2)})$  and  $p$  to be piecewise biquadratic, piecewise biquadratic, and piecewise constant, separately. The periodic conditions are also enforced in the  $y$  direction. The finite element scheme is constructed similarly to (2.5) by artificial compression. Besides, to avoid calculating the integrations in the nonlinear terms repeatedly when we solve the linear equations in every time level by iteration, we approximate the nonlinear terms explicitly (i.e.,  $\delta = 0$ ), in both the spectral-finite element and the finite element schemes, but we always approximate the linear terms implicitly (i.e.,  $\theta = \sigma = 1$ ).

For describing the accuracy, we define the discrete  $L^2$ -normed relative error for  $u^{(1)}$  and  $u^{(2)}$  as

$$E^*(u^{(l)}, t) = \left\{ \frac{\sum_{(x,y) \in \Omega^{(l)}} |U^{(l)}(x, y, t) - u^{(l)}(x, y, t)|^2}{\sum_{(x,y) \in \Omega^{(l)}} |U^{(l)}(x, y, t)|^2} \right\}^{1/2},$$

**TABLE III**

Example (1), with Scheme (2.5),  $M_h = 5, \tau = 10^{-2}, t = 5$

		N = 4		N = 8	
		$E^*(u^{(1)}, t)$	$E^*(u^{(2)}, t)$	$E^*(u^{(1)}, t)$	$E^*(u^{(2)}, t)$
$\beta = 10^{-2}$		2.1396-3	9.7437-4	7.5778-4	8.2725-4
$\beta = 10^{-3}$		2.1379-3	9.8124-4	7.6151-4	8.2940-4
$\beta = 10^{-4}$		2.0537-3	1.1868-3	9.1537-4	1.1504-3

TABLE IV

 Example (2), with Scheme (2.5),  $M_h = 5$ ,  $\tau = 10^{-2}$ ,  $t = 5$ 

	N = 4		N = 8	
	$E^*(u^{(1)}, t)$	$E^*(u^{(2)}, t)$	$E^*(u^{(1)}, t)$	$E^*(u^{(2)}, t)$
$\beta = 10^{-2}$	1.9127-3	6.7048-4	8.9682-4	5.9533-4
$\beta = 10^{-3}$	1.8953-3	6.7098-4	8.9871-4	5.9659-4
$\beta = 10^{-4}$	1.8107-3	1.0813-3	1.5057-3	1.0408-3

where

$$\begin{aligned} \Omega^{(1)} &= \{(x, y)/x = j_1 h_x, y = j_2 h_y, \\ &1 \leq j_1 \leq M_h - 1, 1 \leq j_2 \leq 2N + 1\}, \\ \Omega^{(2)} &= \{(x, y)/x = j_1 h_x/2, y = j_2 h_y/2, \\ &1 \leq j_1 \leq 2M_h - 1, 1 \leq j_2 \leq 2(2N + 1)\}. \end{aligned}$$

The numerical results show that

(1) For the same mesh sizes  $M_h$  and  $N$ , the spectral-finite element scheme gives more accurate results than the finite element scheme does (see Table I and Table II). However, the computing times requires by each are almost the same.

(2) We observe from Theorem 1 that if  $\beta = O(\tau^2)$ , then the artificial compression term  $\beta(\partial P/\partial t)$  does not affect the order of the error  $E^*(u^{(i)}, t)$ . However, in practical computation, the value of  $\beta$  determines the structure of the linear equations derived from scheme (2.5). An excessively small  $\beta$  would result in a large condition number of the corresponding matrix (in fact, the matrix tends to be singular, as  $\beta$  tends to 0) and require a greater amount of computation. Consequently, we should take into account the matrix structure apart from the approximation order, when we select an appropriate  $\beta$ . In the examples in this section, the results for  $\beta = 10^{-2}$  and  $10^{-3}$  are better than that for  $\beta = 10^{-4}$  (see Table III and Table IV).

## V. SOME LEMMAS

To prove Theorem 1, we need the following lemmas.

LEMMA 1. [8]. *If  $r > \frac{1}{2}$ ,  $s \geq 0$ ,  $\bar{r} = \min(r, k + 1)$ , then there exists a positive constant  $c$  independent of  $h$  and  $N$ , such that for all  $\eta \in H_p^{r,s}(\Omega)$ ,*

$$\|\eta - P_N \circ \Pi_h^k \eta\| \leq c(h^{\bar{r}} + N^{-s}) \|\eta\|_{H^{r,s}(\Omega)}.$$

LEMMA 2 [8]. *If  $Nh \leq \text{const}$ ,  $r \geq 1$ ,  $s \geq 1$ ,  $\bar{r} =$*

*$\min(r, k + 1)$ , then there exists a positive constant  $c$  independent of  $h$  and  $N$ , such that for all  $\eta \in M_p^{r,s}(\Omega)$ ,*

$$\|\eta - P_N \circ \Pi_h^k \eta\|_1 \leq c(h^{\bar{r}-1} + N^{1-s}) \|\eta\|_{M^{r,s}(\Omega)}.$$

*In particular, we have for all  $\eta \in H_p^1(\Omega)$  that*

$$\|P_N \circ \Pi_h^k \eta\|_1 \leq c \|\eta\|_1.$$

LEMMA 3. *There exists a linear operator  $Q_\alpha: [H_{0,p}^1(\Omega)]^2 \rightarrow X_\alpha$ , and a positive constant  $c$  independent of  $h$  and  $N$ , such that*

$$(i) \quad b(\eta - Q_\alpha \eta, \omega) = 0, \quad \forall \omega \in Y_\alpha, \forall \eta \in [H_{0,p}^1(\Omega)]^2. \quad (5.1)$$

(ii) *If  $Nh \leq \text{Const}$ , and  $r \geq 1$ ,  $s \geq 1$ , then we have for all  $\eta \in [M^{r,s}(\Omega)]^2$  that*

$$\begin{aligned} \|\eta - Q_\alpha \eta\|_1 &\leq c(h^{\bar{r}-1} + N^{1-s}) \|\eta\|_{M^{r,s}(\Omega)}, \\ \bar{r} &= \min(r, k + 2), \end{aligned} \quad (5.2)$$

$$\|Q_\alpha \eta\|_1 \leq c \|\eta\|_1. \quad (5.3)$$

*Proof.* Let

$$\eta = \begin{pmatrix} \eta^{(1)} \\ \eta^{(2)} \end{pmatrix} = \sum_{|j|=0}^{\infty} \begin{pmatrix} \eta_j^{(1)}(x) \\ \eta_j^{(2)}(x) \end{pmatrix} e^{iy} \in (H_{0,p}^1(\Omega))^2.$$

We have from Sobolev's embedding theorem that  $H_{0,p}^1(\Omega) \hookrightarrow \mathcal{L}^2(\bar{I}, C(I))$ . Hence

$$\eta_j^{(m)} \in C(I), \quad \forall |j| < \infty, \quad m = 1, 2.$$

Let

$$Q_\alpha \eta = \begin{pmatrix} Q_\alpha^{(1)} \eta^{(1)} \\ Q_\alpha^{(2)} \eta^{(2)} \end{pmatrix} = \sum_{|j| \leq N} \begin{pmatrix} Q_h^{(1)} \eta_j^{(1)}(x) \\ Q_h^{(2)} \eta_j^{(2)}(x) \end{pmatrix} e^{iy},$$

where  $Q_h^{(m)} \eta_j^{(m)} \in S_h^{k+m}$ ,  $m = 1, 2$ , are defined by

$$\begin{aligned} Q_h^{(m)} \eta_j^{(m)}(x_l) &= \eta_j^{(m)}(x_l), \quad 0 \leq l \leq M_h, \\ \int_{I_l} [Q_h^{(m)} \eta_j^{(m)}(x) - \eta_j^{(m)}(x)] \omega(x) dx &= 0, \end{aligned} \quad (5.4)$$

$$\forall \omega \in P_{k+m-2}, \quad 1 \leq l \leq M_h.$$

It is obvious that  $Q_\alpha$  is a well-defined linear operator from  $[H_{0,p}^1(\Omega)]^2$  onto  $X_\alpha$ .

We first prove (5.1). Suppose

$$\omega = \sum_{|j| \leq N} \omega_j(x) e^{iy} \in Y_\alpha.$$

Then we have  $\omega_j \in \tilde{S}_h^k$ , and hence  $\omega_j|_{I_l} \in P_k$ . Thus we have from (5.4) that

$$\begin{aligned} & b(\eta - Q_x \eta, \omega) \\ &= \sum_{|j| \leq N} \int_I \left[ \frac{\partial}{\partial x} (\eta_j^{(1)} - Q_h^{(1)} \eta_j^{(1)})(x) \right. \\ &\quad \left. + ij(\eta_j^{(2)} - Q_h^{(2)} \eta_j^{(2)})(x) \right] \omega_j(x) dx \\ &= \sum_{|j| \leq N} \sum_{1 \leq l \leq M_n} \int_{I_l} \left[ -(\eta_j^{(1)}(x) - Q_h^{(1)} \eta_j^{(1)}(x)) \right. \\ &\quad \left. \times \frac{\partial \omega_j}{\partial x}(x) + ij(\eta_j^{(2)}(x) - Q_h^{(2)} \eta_j^{(2)}(x)) \omega(x) \right] dx \\ &= 0. \end{aligned}$$

Next we prove (5.2). Consider the reference element  $\hat{I} = [0, 1]$ , and a linear operator  $\hat{Q}: C(\hat{I}) \rightarrow P_{k'+2}$  ( $k' = k$  or  $k - 1$ ) defined as: for any  $\hat{\xi} \in C(\hat{I})$ ,  $\hat{Q}\hat{\xi} \in P_{k'+2}$  satisfies

$$\begin{aligned} \hat{Q}\hat{\xi}(x) &= \hat{\xi}(x), \quad x = 0, 1, \\ \int_{\hat{I}} (\hat{Q}\hat{\xi}(x) - \hat{\xi}(x)) \omega(x) dx &= 0, \quad \forall \omega \in P_{k'}. \end{aligned} \tag{5.5}$$

It is not difficult to verify that

$$\hat{Q} \in \mathcal{L}(C(\hat{I}), W^{m,q}(\hat{I})), \quad \forall m \geq 0, q \geq 1, \tag{5.5}$$

and

$$\hat{Q}\hat{\xi} = \hat{\xi}, \quad \forall \hat{\xi} \in P_{k'+2}. \tag{5.6}$$

Moreover, we define the operator  $F: \hat{I} \rightarrow I_l$  by

$$x = F(\hat{x}) = h_l \hat{x} + x_{l-1}.$$

and a correspondence between  $C(\hat{I})$  and  $C(I_l)$ , i.e., for any  $\xi \in C(I_l)$ ,

$$\hat{\xi}(\hat{x}) = \xi(F^{-1}(x)) = \xi(x).$$

Then we can prove for any  $Q_{h,l}$ , the restriction of  $Q_h^{(m)}$  ( $m = 1$  or  $2$ ) on  $I_l$ , that

$$\widehat{Q_{h,l}\xi} = \hat{Q}\hat{\xi}. \tag{5.7}$$

In fact,

$$\widehat{Q_{h,l}\xi}(0) = Q_{h,l}\xi(x_{l-1}) = \xi(x_{l-1}) = \hat{\xi}(0) = \hat{Q}\hat{\xi}(0),$$

and, similarly,  $\widehat{Q_{h,l}\xi}(1) = \hat{Q}\hat{\xi}(1)$ . Besides, we have

$$\begin{aligned} & \int_I (\widehat{Q_{h,l}\xi} - \hat{\xi})(\hat{x}) \hat{\omega}(\hat{x}) d\hat{x} \\ &= \frac{1}{h_l} \int_{I_l} (Q_{h,l}\xi - \xi)(x) \omega(x) dx \\ &= 0, \quad \forall \hat{\omega} \in P_{k'}. \end{aligned}$$

The uniqueness of  $\hat{Q}$  assures the validity of (5.7).

By an argument analogous to the classical error estimation for function interpolation (see [18]), we obtain from (5.5)–(5.7) that

$$\begin{aligned} \|\eta_j^{(m)} - Q_h^{(m)} \eta_j^{(m)}\| &\leq ch^{\bar{r}_m} |\eta_j^{(m)}|_{H^{\bar{r}_m(I)}}, \\ |\eta_j^{(m)} - Q_h^{(m)} \eta_j^{(m)}|_1 &\leq ch^{\bar{r}_m - 1} |\eta_j^{(m)}|_{H^{\bar{r}_m(I)}}, \end{aligned}$$

where  $\bar{r}_m = \min(r, k + m + 1)$ . Thus we have

$$\begin{aligned} \|\eta - Q_x \eta\|_1^2 &= \sum_{m=1}^2 \left\{ \sum_{|j| \leq N} [|\eta_j^{(m)} - Q_j^{(m)} \eta_j^{(m)}|_1^2 \right. \\ &\quad \left. + j^2 \|\eta_j^{(m)} - Q_h^{(m)} \eta_j^{(m)}\|^2] \right. \\ &\quad \left. + \sum_{|j| > N} [|\eta_j^{(m)}|_1^2 + j^2 \|\eta_j^{(m)}\|^2] \right\} \\ &\leq \sum_{m=1}^2 \left\{ ch^{2(\bar{r}-1)} \sum_{|j| \leq N} [|\eta_j^{(m)}|_{H^{\bar{r}(I)}}^2 \right. \\ &\quad \left. + h^2 j^2 |\eta_j^{(m)}|_{H^{\bar{r}(I)}}^2] \right. \\ &\quad \left. + cN^{2(1-s)} \sum_{|j| > N} [ |j|^{2(s-1)} |\eta_j^{(m)}|_1^2 \right. \\ &\quad \left. + |j|^{2s} \|\eta_j^{(m)}\|^2] \right\} \\ &\leq c(h^{2(\bar{r}-1)} + N^{2(1-s)}) \|\eta\|_{M^{\bar{r},s}(\Omega)}^2, \end{aligned}$$

with  $\bar{r} = \min(\bar{r}_1, \bar{r}_2) = \min(r, k + 2)$ .

Finally, we can obtain (5.3) by putting  $r = s = 1$  in (5.2).

LEMMA 4. *There exists a positive constant  $C_d$ , depending on the parameter  $d$ , but not on  $h$  and  $N$ , such that for all  $\eta \in S_h^{k+m} \otimes S_N$ ,  $m = 1, 2$ ,*

$$\|\eta\|_{L^\infty(\Omega)} \leq c_d h^{-1/2} N^{1/2} \|\eta\|, \tag{5.8}$$

$$\|\eta\|_1 \leq (c_d h^{-2} + N^2)^{1/2} \|\eta\|. \tag{5.9}$$

*Proof.* Let

$$\eta = \sum_{|j| \leq N} \eta_j(x) e^{ijy} \in S_h^{k+m} \otimes S_N;$$

then  $\eta_j \in S_h^{k+m}$ . Thus by the inverse inequality in the finite element method, we have [18]

$$\begin{aligned}\|\eta_j\|_{L^\infty(\Omega)} &\leq c_d h^{-1/2} \|\eta_j\|, \\ |\eta_j|_1 &\leq c_d h^{-1} \|\eta_j\|,\end{aligned}$$

and hence

$$\begin{aligned}\|\eta\|_{L^\infty(\Omega)} &\leq \sum_{|j| \leq N} |\eta_j|_{L^\infty(\Omega)} \\ &\leq c_d h^{-1/2} \sum_{|j| \leq N} \|\eta_j\| \\ &\leq c_d h^{-1/2} N^{1/2} \left( \sum_{|j| \leq N} \|\eta_j\|^2 \right)^{1/2} \\ &\leq c_d h^{-1/2} N^{1/2} \|\eta\|, \\ |\eta|_1 &= \left[ \sum_{|j| \leq N} (|\eta_j|_1^2 + j^2 \|\eta_j\|^2) \right]^{1/2} \\ &\leq \left[ \sum_{|j| \leq N} (c_d h^{-2} \|\eta_j\|^2 + N^2 \|\eta_j\|^2) \right]^{1/2} \\ &\leq (c_d h^{-2} + N^2)^{1/2} \|\eta\|.\end{aligned}$$

LEMMA 5. *There exists a positive constant  $c$  depending only on  $\Omega$ , such that for all  $\eta, \xi, \varphi \in [H_{0,p}^1(\Omega)]^2$ ,*

$$|J(\eta, \varphi, \xi)| \leq c |\eta|_1 |\xi|_1 \|\varphi\|^{1/2} |\varphi|_1^{1/2}, \quad (5.10)$$

$$\begin{aligned}|J(\eta, \varphi, \xi)| &\leq c |\varphi|_1 (|\eta|_1 \|\xi\|^{1/2} |\xi|_1^{1/2} \\ &\quad + \|\eta\|^{1/2} |\eta|_1^{1/2} |\xi|_1), \quad (5.11)\end{aligned}$$

$$|J(\eta, \varphi, \xi)| \leq c |\eta|_1 |\xi|_1 |\varphi|_1. \quad (5.12)$$

*Proof.* We have from Sobolev's embedding theorem that  $H^1(\Omega) \hookrightarrow \mathcal{L}^6(\Omega)$ . By the equivalence of the norm  $\|\cdot\|_1$  and the semi-norm  $|\cdot|_1$  over  $H_{0,p}^1(\Omega)$ , and Hölder's inequality, we have

$$\|\varphi\|_{\mathcal{L}^3(\Omega)} \leq \|\varphi\|_{\mathcal{L}^2(\Omega)}^{1/2} \|\varphi\|_{\mathcal{L}^6(\Omega)}^{1/2} \leq c \|\varphi\|^{1/2} |\varphi|_1^{1/2}.$$

Hence

$$\begin{aligned}|J(\eta, \varphi, \xi)| &\leq \frac{1}{2} \int_{\Omega} |((\varphi \cdot \nabla) \eta) \xi| \, d\Omega \\ &\quad + \frac{1}{2} \int_{\Omega} |((\varphi \cdot \nabla) \xi) \eta| \, d\Omega \\ &\leq c |\eta|_1 \|\xi\|_{\mathcal{L}^6(\Omega)} \|\varphi\|_{\mathcal{L}^3(\Omega)} \\ &\quad + c |\xi|_1 \|\eta\|_{\mathcal{L}^6(\Omega)} \|\varphi\|_{\mathcal{L}^3(\Omega)} \\ &\leq c |\eta|_1 |\xi|_1 \|\varphi\|^{1/2} |\varphi|_1^{1/2}.\end{aligned}$$

Inequality (5.11) can be proved similarly; (5.12) can be obtained readily by (5.10) and  $\|\varphi\| \leq c |\varphi|_1$ .

LEMMA 6 [19]. *Suppose that the following conditions are fulfilled,*

(i)  $Z(t)$  is a non-negative function defined on  $S_\tau, D_1, D_2$ , and  $\rho$  are non-negative constants,

(ii)  $H$  is a real-valued function defined on  $R^1$ , such that  $H(\xi) \leq 0$  for  $\xi \in D_2$ ,

(iii) for all  $t \in S_\tau$ ,

$$Z(t) \leq \rho + \sum_{t' \leq t-\tau} [D_1 Z(t') + H(Z(t'))],$$

(iv)  $Z(0) \leq \rho$ , and  $\rho e^{D_1 t_1} \leq D_2$ , for some  $t_1 \in S_\tau$ ; then, we have for all  $t \leq t_1$  that

$$Z(t) \leq \rho e^{D_1 t}.$$

In particular, if  $H(\xi) \leq 0$  for all  $\xi \in R^1$ , then the above inequality holds for all  $t \in S_\tau$  and any  $\rho$ .

## VI. THE PROOF OF CONVERGENCE

Let the pair  $(U, P)$  be the solution of (2.4). Assume that they are suitably smooth. Let

$$u^*(t) = Q_\alpha U(t), \quad p^*(t) = \varphi_\alpha P(t).$$

Then we have from (2.4) and (5.1) that

$$\begin{aligned}(u_t^*(t), v) + J(u^*(t) + \delta\tau u_t^*(t), u^*(t), v) \\ - b(v, p^*(t) + \theta\tau p_t^*(t)) \\ + va(u^*(t) + \sigma\tau u_t^*(t), v) \\ = (P_N \circ \Pi_h^k f(t), v) + \sum_{i=1}^8 E_i(v), \quad (6.1)\end{aligned}$$

$$\forall v \in (H_{0,p}^1(\Omega))^2,$$

$$\beta(p_t^*(t), \omega) + b(u^*(t) + \theta\tau u_t^*(t), \omega)$$

$$= E_9(\omega), \quad \forall \omega \in \tilde{\mathcal{L}}^2(\Omega),$$

$$u^*(0) = Q_\alpha U_0, \quad p^*(0) = \varphi_\alpha P(0),$$

where

$$E_1(v) = \left( u_t^* - \frac{\partial U}{\partial t}, v \right),$$

$$E_2(v) = J(u^*, u^*, v) - J(U, U, v),$$

$$E_3(v) = \delta\tau J(u^*, u^*, v),$$

$$E_4(v) = b(v, P - p^*),$$

$$\begin{aligned}
 E_5(v) &= -\theta\tau b(v, p_t^*), \\
 E_6(v) &= va(u^* - U, v), \\
 E_7(v) &= v\sigma\tau a(u_t^*, v), \\
 E_8(v) &= (f - P_N \circ \Pi_h^k f, v), \\
 E_9(\omega) &= \beta(p_t^*, \omega).
 \end{aligned}$$

where

$$\begin{aligned}
 F_1 &= 2J(u^* + \delta\tau u_t^*, \tilde{u}, \tilde{u}), \\
 F_2 &= m\tau J(u^* + \delta\tau u_t^*, \tilde{u}, \tilde{u}_t), \\
 F_3 &= \tau(m - 2\delta) J(\tilde{u}, u^*, \tilde{u}_t), \\
 F_4 &= \tau(m - 2\delta) J(\tilde{u}, \tilde{u}, \tilde{u}_t).
 \end{aligned}$$

Let the pair  $(u, p)$  be the solution of (2.5). Define

$$\tilde{u}(t) = u(t) - u^*(t), \quad \tilde{p}(t) = p(t) - p^*(t).$$

By subtracting (2.5) from (6.1), we obtain that

$$\begin{aligned}
 &(\tilde{u}_t(t), v) + J(u^*(t) + \delta\tau u_t^*(t), \tilde{u}(t), v) \\
 &\quad + J(\tilde{u}(t) + \delta\tau \tilde{u}_t(t), u^*(t) + \tilde{u}(t), v) \\
 &\quad - b(v, \tilde{p}(t) + \theta\tau \tilde{p}_t(t)) \\
 &\quad + va(\tilde{u}(t) + \sigma\tau \tilde{u}_t(t), v) \\
 &= -\sum_{l=1}^8 E_l(v), \quad \forall v \in X_\alpha, \tag{6.2}
 \end{aligned}$$

$$\begin{aligned}
 &\beta(\tilde{p}_t(t), \omega) + b(\tilde{u}(t) + \theta\tau \tilde{u}_t(t), \omega) \\
 &= -E_9(\omega), \quad \forall \omega \in Y_\alpha, \\
 &\tilde{u}(0) = -Q_\alpha U_0 + P_N \circ \Pi_h^{k+1} U_0, \\
 &\tilde{p}(0) = -\varphi_\alpha P(0).
 \end{aligned}$$

Let  $m > 1$  be a undetermined constant. Noting (3.1) and the identity [19]

$$2(\tilde{u}_t(t), \tilde{u}(t)) = (\|\tilde{u}(t)\|^2)_t - \tau \|\tilde{u}_t(t)\|^2, \tag{6.3}$$

we have by taking  $v = 2\tilde{u}(t) + m\tau \tilde{u}_t(t)$  in the first equation of (6.2) that

$$\begin{aligned}
 &(\|\tilde{u}(t)\|^2)_t + \tau(m - 1)\|\tilde{u}_t(t)\|^2 + 2v \|\tilde{u}_t(t)\|_1^2 \\
 &\quad + v\tau \left(\sigma + \frac{m}{2}\right) (\|\tilde{u}_t(t)\|_1^2)_t \\
 &\quad + v\tau^2 \left(m\sigma - \sigma - \frac{m}{2}\right) \|\tilde{u}_t(t)\|_1^2 \\
 &\quad + \sum_{l=1}^4 F_l(t) - b(2\tilde{u}(t) + m\tau \tilde{u}_t(t), \tilde{p}(t) + \theta\tau \tilde{p}_t(t)) \\
 &= -\sum_{l=1}^8 E_l(2\tilde{u}(t) + m\tau \tilde{u}_t(t)), \tag{6.4}
 \end{aligned}$$

By taking  $\omega = 2\tilde{p}(t) + m\tau \tilde{p}_t(t)$  in the second equation of (6.2), we have from (6.3) that

$$\begin{aligned}
 &\beta(\|\tilde{p}(t)\|^2)_t + \beta\tau(m - 1) \|\tilde{p}_t(t)\|^2 \\
 &\quad + b(\tilde{u}(t) + \theta\tau \tilde{u}_t(t), 2\tilde{p}(t) + m\tau \tilde{p}_t(t)) \\
 &= -E_9(2\tilde{p}(t) + m\tau \tilde{p}_t(t)). \tag{6.5}
 \end{aligned}$$

By putting (6.4) and (6.5) together, we obtain

$$\begin{aligned}
 &(\|\tilde{u}(t)\|^2 + \beta \|\tilde{p}(t)\|^2)_t + \tau(m - 1) (\|\tilde{u}_t(t)\|^2 \\
 &\quad + \beta \|\tilde{p}_t(t)\|^2) + 2v \|\tilde{u}_t(t)\|_1^2 \\
 &\quad + v\tau \left(\sigma + \frac{m}{2}\right) (\|\tilde{u}_t(t)\|_1^2)_t \\
 &\quad + v\tau^2 \left(m\sigma - \sigma - \frac{m}{2}\right) \|\tilde{u}_t(t)\|_1^2 \\
 &\quad + \sum_{l=1}^4 F_l(t) + \tau(2\theta - m) H(t) \\
 &= -\sum_{l=1}^8 E_l(2\tilde{u}(t) + m\tau \tilde{u}_t(t)) \\
 &\quad - E_9(2\tilde{p}(t) + m\tau \tilde{p}_t(t)), \tag{6.6}
 \end{aligned}$$

where

$$H(t) = b(\tilde{u}_t, \tilde{p}) - b(\tilde{u}, \tilde{p}_t).$$

We now estimate  $|F_l|$ . Suppose  $\varepsilon > 0$  is a suitably small constant. Then we have from (5.3) and (5.10) that

$$\begin{aligned}
 |F_1| &\leq c |u^* + \delta\tau u_t^*|_1 \|\tilde{u}\|^{1/2} |\tilde{u}|_1^{3/2} \\
 &\leq c \|U\|_{C(0, T; H^1(\Omega))} \|\tilde{u}\|^{1/2} |\tilde{u}|_1^{3/2} \\
 &\leq \frac{1}{2} \varepsilon v |\tilde{u}|_1^2 \\
 &\quad + \frac{c}{\varepsilon v} \|U\|_{C(0, T; H^1(\Omega))}^2 \|\tilde{u}\| |\tilde{u}|_1 \\
 &\leq \varepsilon v |\tilde{u}|_1^2 + \frac{C}{\varepsilon^3 v^3} \|U\|_{C(0, T; H^1(\Omega))}^4 \|\tilde{u}\|^2,
 \end{aligned}$$



and

$$\begin{aligned}
 |F_2| &\leq c m \tau \|U\|_{C(0, T; H^1(\Omega))} \\
 &\quad \times \|\tilde{u}\|^{1/2} |\tilde{u}|_1^{1/2} |\tilde{u}_t|_1 \\
 &\leq \varepsilon v \tau |\tilde{u}|_1 |\tilde{u}_t|_1 \\
 &\quad + \frac{c \tau m^2}{\varepsilon v} \|U\|_{C(0, T; H^1(\Omega))}^2 \|\tilde{u}\| |\tilde{u}_t|_1 \\
 &\leq \varepsilon v |\tilde{u}|_1^2 + \varepsilon v \tau^2 |\tilde{u}_t|_1^2 \\
 &\quad + \frac{c m^4}{\varepsilon^3 v^3} \|U\|_{C(0, T; H^1(\Omega))}^4 \|\tilde{u}\|^2.
 \end{aligned}$$

Similarly, we can obtain from (5.11) that

$$\begin{aligned}
 |F_3| &\leq c \tau |m - 2\delta| |u^*|_1 \\
 &\quad \times (|\tilde{u}|_1 \|\tilde{u}_t\|^{1/2} |\tilde{u}_t|_1^{1/2} \\
 &\quad + \|\tilde{u}\|^{1/2} |\tilde{u}|_1^{1/2} |\tilde{u}_t|_1) \\
 &\leq \varepsilon v \tau |\tilde{u}|_1 |\tilde{u}_t|_1 \\
 &\quad + \frac{c \tau (m - 2\delta)^2}{\varepsilon v} \|U\|_{C(0, T; H^1(\Omega))}^2 \\
 &\quad \times (\|\tilde{u}\| |\tilde{u}_t|_1 + |\tilde{u}|_1 \|\tilde{u}_t\|) \\
 &\leq \varepsilon v |\tilde{u}|_1^2 + \varepsilon v \tau^2 |\tilde{u}_t|_1^2 \\
 &\quad + \varepsilon \tau \|\tilde{u}_t\|^2 + \frac{c(m - 2\delta)^4}{\varepsilon^3 v^3} \\
 &\quad \times \|U\|_{C(0, T; H^1(\Omega))}^4 (\|\tilde{u}\|^2 + \tau |\tilde{u}|_1^2).
 \end{aligned}$$

From integrating by parts in  $F_4$ , we have by (5.8) that

$$\begin{aligned}
 |F_4| &= \tau |m - 2\delta| \left| \int_{\Omega} [((\tilde{u} \cdot \nabla) \tilde{u}) \tilde{u}_t \right. \\
 &\quad \left. + \frac{1}{2} (\nabla \cdot \tilde{u})(\tilde{u} \cdot \tilde{u}_t)] d\Omega \right| \\
 &\leq c \tau |m - 2\delta| \|\tilde{u}\|_{\mathcal{L}^\infty(\Omega)} |\tilde{u}|_1 \|\tilde{u}_t\| \\
 &\leq \varepsilon \tau \|\tilde{u}_t\|^2 + \frac{c \tau N(m - 2\delta)^2}{\varepsilon h} \|\tilde{u}\|^2 |\tilde{u}|_1^2.
 \end{aligned}$$

Next we examine  $|E_i|$ . First, we have

$$\begin{aligned}
 |E_1(2\tilde{u} + m\tau\tilde{u}_t)| &\leq \|\tilde{u}\|^2 + \varepsilon \tau \|\tilde{u}_t\|^2 \\
 &\quad + \left(1 + \frac{\tau m^2}{4\varepsilon}\right) \left\| u_t^* - \frac{\partial U}{\partial t} \right\|^2.
 \end{aligned}$$

We have, furthermore, from (5.12) that

$$\begin{aligned}
 |E_2(2\tilde{u} + m\tau\tilde{u}_t)| &\leq |J(U, u^* - U, 2\tilde{u} + m\tau\tilde{u}_t)| \\
 &\quad + |J(u^* - U, u^*, 2\tilde{u} + m\tau\tilde{u}_t)| \\
 &\leq c |U|_1 |u^* - U|_1 |2\tilde{u} + m\tau\tilde{u}_t|_1 \\
 &\leq \varepsilon v |\tilde{u}|_1^2 + \varepsilon v \tau^2 |\tilde{u}_t|_1^2 \\
 &\quad + \frac{c}{\varepsilon v} \left(1 + \frac{m^2}{4}\right) \\
 &\quad \times \|U\|_{C(0, T; H^1(\Omega))}^2 |u^* - U|_1^2
 \end{aligned}$$

and

$$\begin{aligned}
 |E_3(2\tilde{u} + m\tau\tilde{u}_t)| &\leq c \delta \tau |u_t^*|_1 |\tilde{u}|_1 |2\tilde{u} + m\tau\tilde{u}_t|_1 \\
 &\leq \varepsilon v |\tilde{u}|_1^2 + \varepsilon v \tau^2 |\tilde{u}_t|_1^2 \\
 &\quad + \frac{c \delta^2 \tau^2}{\varepsilon v} \left(1 + \frac{m^4}{4}\right) |U_t|_1^2 |\tilde{u}|_1^2.
 \end{aligned}$$

Besides, it is not difficult to show that

$$\begin{aligned}
 \sum_{i=4}^7 |E_i(2\tilde{u} + m\tau\tilde{u}_t)| &\leq \varepsilon v |\tilde{u}|_1^2 + \varepsilon v \tau^2 |\tilde{u}_t|_1^2 \\
 &\quad + \frac{c}{\varepsilon v} \left(1 + \frac{m^4}{4}\right) (\|p^* - P\|^2 \\
 &\quad + v |u^* - U|_1^2 + \theta^2 \tau^2 \|p_t^*\|^2 \\
 &\quad + v \sigma^2 \tau^2 |U_t|_1^2), \\
 |E_8(2\tilde{u} + m\tau\tilde{u}_t)| &\leq \|\tilde{u}\|^2 + \varepsilon \tau \|\tilde{u}_t\|^2 \\
 &\quad + \left(1 + \frac{\tau m^2}{4\varepsilon}\right) \|f - P_N \circ \Pi_h^k f\|^2, \\
 |E_9(2\tilde{p} + m\tau\tilde{p}_t)| &\leq \beta \|\tilde{p}\|^2 + \varepsilon \beta \tau \|\tilde{p}_t\|^2 \\
 &\quad + \beta \left(1 + \frac{\tau m^2}{4\varepsilon}\right) \|p_t^*\|^2.
 \end{aligned}$$

By substituting the above estimations into (6.6), we obtain

$$\begin{aligned}
 &(\|\tilde{u}(t)\|^2 + \beta \|\tilde{p}(t)\|^2)_t + \tau(m - 1 - 5\varepsilon)(\|\tilde{u}_t(t)\|^2 \\
 &\quad + \beta \|\tilde{p}_t(t)\|^2) + v(1 - 6\varepsilon) |\tilde{u}(t)|_1^2 \\
 &\quad + v \tau \left(\sigma + \frac{m}{2}\right) (|\tilde{u}(t)|_1^2)_t \\
 &\quad + v \tau^2 \left(m\sigma - \sigma - \frac{m}{2} - 5\varepsilon\right) |\tilde{u}_t(t)|_1^2 \\
 &\quad + \tau(2\theta - m) H(t) \\
 &\leq C_1 (\|\tilde{u}(t)\|^2 + \beta \|\tilde{p}(t)\|^2) \\
 &\quad + C_2(t) |\tilde{u}(t)|_1^2 + G(t), \tag{6.7}
 \end{aligned}$$

where

$$\begin{aligned}
 C_1 &= 2 + \frac{c(1+m^4+(m-2\delta)^4)}{\varepsilon^3\nu^3} \|U\|_{C(0,T;H^1(\Omega))}^4, \\
 C_2(t) &= -\nu + \frac{c\tau(m-2\delta)^4}{\varepsilon^3\nu^3} \|U\|_{C(0,T;H^1(\Omega))}^4 \\
 &\quad + \frac{c\delta^2\tau^2}{\varepsilon\nu} \left(1 + \frac{m^2}{4}\right) \|U_t(t)\|^2 \\
 &\quad + \frac{c\tau N(m-2\delta)^2}{\varepsilon h} \|\tilde{u}(t)\|^2, \\
 G(t) &= \left(1 + \frac{\tau m^2}{4\varepsilon}\right) \left\|u_t^* - \frac{\partial U}{\partial t}\right\|^2 \\
 &\quad + \beta \|p_t^*(t)\|^2 + \|f(t) - P_N \circ \Pi_h^k f(t)\|^2 \\
 &\quad + \frac{c}{\varepsilon\nu} \left(1 + \frac{m^4}{4}\right) \left[\nu + \|U\|_{C(0,T;H^1(\Omega))}^2\right] \\
 &\quad \times |u^*(t) - U(t)|_1^2 + \|p_t^*(t) - P(t)\|^2 \\
 &\quad + \nu\sigma^2\tau^2 |U_t(t)|_1^2 + \theta^2\tau^2 \|p_t^*(t)\|^2.
 \end{aligned}$$

Now we choose the constants  $m$  and  $\varepsilon$ . Take  $m = 2\theta$  and  $r_0 \geq 0$  to be sufficiently small. If  $\sigma > \frac{1}{2}$  and  $\theta > \sigma/(2\sigma - 1)$ , then we can take  $\varepsilon$  and  $r_0$  to be so small that

$$2\theta \geq \max\left(1 + 4\varepsilon + r_0, \frac{2\sigma + 10\varepsilon}{2\sigma - 1}\right).$$

If  $\sigma \leq \theta/(2\theta - 1)$ , and

$$\nu\tau(C_d h^{-2} + N^2) < \frac{2\theta - 1}{\sigma + \theta(1 - 2\sigma)}, \tag{6.8}$$

then we take  $\varepsilon$  and  $r_0$  to be so small that

$$\begin{aligned}
 2\theta - 1 - 4\varepsilon - r_0 &\geq \nu\tau[2\theta(\frac{1}{2} - \sigma) + \sigma + 5\varepsilon] \\
 &\quad \times (C_d h^{-2} + N^2).
 \end{aligned}$$

By (5.9), we have in both cases that

$$\begin{aligned}
 &\tau(m - 1 - 4\varepsilon)(\|\tilde{u}_t(t)\|^2 + \beta \|\tilde{p}_t(t)\|^2) \\
 &\quad + \nu\tau^2 \left(m\sigma - \sigma - \frac{m}{2} - 5\varepsilon\right) |\tilde{u}_t(t)|_1^2 \\
 &\geq r_0\tau(\|\tilde{u}_t(t)\|^2 + \beta \|\tilde{p}_t(t)\|^2).
 \end{aligned}$$

Consequently, we obtain from (6.7) that

$$\begin{aligned}
 &(\|\tilde{u}(t)\|^2 + \beta \|\tilde{p}(t)\|^2)_t + r_0\tau(\|\tilde{u}_t(t)\|^2 \\
 &\quad + \beta \|\tilde{p}_t(t)\|^2) + \nu(1 - 6\varepsilon) |\tilde{u}(t)|_1^2 \\
 &\quad + \nu\tau \left(\sigma + \frac{m}{2}\right) (|\tilde{u}(t)|_1^2)_t \\
 &\leq C_1(\|\tilde{u}(t)\|^2 + \beta \|\tilde{p}(t)\|^2) \\
 &\quad + C_2(t) |\tilde{u}(t)|_1^2 + G(t). \tag{6.9}
 \end{aligned}$$

Let  $E(\eta, \xi, t)$  be defined as in Section III, and

$$\begin{aligned}
 \rho(t) &= \|\tilde{u}(0)\|^2 + \beta \|\tilde{p}(0)\|^2 + \nu\tau \left(\sigma + \frac{m}{2}\right) |\tilde{u}(0)|_1^2 \\
 &\quad + \tau \sum_{t' \leq t-\tau} G(t').
 \end{aligned}$$

By summing (6.9) for all  $t' \leq t - \tau$ ,  $t' \in S_\tau$ , we obtain

$$\begin{aligned}
 E(\tilde{u}, \tilde{p}, t) &\leq \rho(t) + \tau \sum_{t' \leq t-\tau} (C_1 E(\tilde{u}, \tilde{p}, t') \\
 &\quad + C_2(t') |\tilde{u}(t')|_1^2). \tag{6.10}
 \end{aligned}$$

Clearly, if the mesh size  $\tau$  is sufficiently small, then we have

$$C_2(t) \leq -\frac{\nu}{2} + \frac{c\tau N(m-2\delta)^2}{\varepsilon h} \|\tilde{u}(t)\|^2.$$

Hence we have from Lemma 6 that if there exists a  $t_1 \in S_\tau$  such that

$$\rho(t_1) \leq \frac{\varepsilon\nu h}{2c\tau N(m-2\delta)^2}, \tag{6.11}$$

then we have for all  $t \leq t_1$ ,  $t \in S_\tau$ ,

$$E(\tilde{u}, \tilde{p}, t) \leq \rho(t) e^{C_1 t}.$$

Thus, in order to obtain the convergence, we only need to obtain the order of  $\rho(t)$  and verify (6.11).

By Lemma 2 and (5.2), we have

$$\begin{aligned}
 \|\tilde{u}(0)\| &\leq c |\tilde{u}(0)|_1 \leq c(|U(0) - Q_x U(0)|_1 \\
 &\quad + |U(0) - P_N \circ \Pi_h^{k+1} U(0)|_1) \\
 &\leq c(h^{\bar{r}-1} + N^{1-s}) \|U(0)\|_{M^{\bar{r},s}(\Omega)}, \\
 \bar{r} &= \min(r, k + 2),
 \end{aligned}$$

$$|u^*(t) - U(t)|_1 \leq c(h^{\bar{r}-1} + N^{1-s}) \|U(t)\|_{M^{\bar{r},s}(\Omega)}.$$

By Lemma 1, we have

$$\begin{aligned} \|\tilde{p}(0)\| &\leq c \|P(0)\|, \\ \|p^*(t) - P(t)\| &\leq c(h^{\bar{r}-1} + N^{1-s}) \\ &\quad \times \|P(t)\|_{H^{\bar{r}-1, s-1}(\Omega)}, \\ \|f(t) - P_N \circ \Pi_h^k f(t)\| &\leq c(h^{\bar{r}-1} + N^{1-s}) \\ &\quad \times \|f(t)\|_{H^{\bar{r}+1, s-1}(\Omega)}. \end{aligned}$$

By using Taylor's formula, we obtain that

$$\begin{aligned} |U_i(t)|_1 &= \frac{1}{\tau} \left| \int_t^{t+\tau} \frac{\partial U}{\partial t}(t') dt' \right|_1 \\ &\leq \tau^{-1/2} \left( \int_t^{t+\tau} \left| \frac{\partial U}{\partial t}(t') \right|_1^2 dt' \right)^{1/2}, \end{aligned}$$

and, similarly,

$$\begin{aligned} \|p_i^*(t)\| &\leq c \|P_i(t)\| \\ &\leq c\tau^{-1/2} \left( \int_t^{t+\tau} \left\| \frac{\partial P}{\partial t}(t') \right\|^2 dt' \right)^{1/2}. \end{aligned}$$

Besides, it is not difficult to show that

$$\begin{aligned} \left\| u_i^*(t) - \frac{\partial U}{\partial t}(t) \right\| &\leq \|U_i(t) - u_i^*(t)\| + \left\| U_i(t) - \frac{\partial U}{\partial t}(t) \right\| \\ &\leq \frac{1}{\tau} \int_t^{t+\tau} \left\| \frac{\partial}{\partial t}(U - u^*)(t') \right\| dt' \\ &\quad + \frac{1}{\tau} \int_t^{t+\tau} \int_t^{t'} \left\| \frac{\partial^2 U}{\partial t^2}(t'') \right\| dt'' dt' \\ &\leq c\tau^{-1/2} (h^{\bar{r}-1} + N^{1-s}) \\ &\quad \times \left[ \int_t^{t+\tau} \left\| \frac{\partial U}{\partial t}(t') \right\|_{H^{\bar{r}-1, s-1}(\Omega)}^2 dt' \right]^{1/2} \\ &\quad + c\tau^{-1/2} \left( \int_t^{t+\tau} \left\| \frac{\partial^2 U}{\partial t^2}(t') \right\|^2 dt' \right)^{1/2}. \end{aligned}$$

Thus we have from the above estimates that

$$\rho(t) \leq C^*(\tau^2 + h^{2(\bar{r}-1)} + N^{2(1-s)} + \beta),$$

where the constant  $C^*$  is described in Theorem 1.

Finally, we show that if  $h, N^{-1}, \tau$ , and  $\beta$  are sufficiently small and satisfy some conditions, then (6.11) holds for  $t_1 = T$ . In fact, suppose  $\beta = O(\tau^2)$ ,  $h = O(N^{-\mu})$ , and  $\tau = O(N^{-\lambda})$ , with  $\lambda, \mu > 0$ . If (3.1) holds for  $\theta > \sigma/(2\sigma - 1)$ , then we have

$$\begin{aligned} \tau N h^{-1} (\tau^2 + h^{2(\bar{r}-1)} + N^{2(1-s)} + \beta) &\rightarrow 0, \\ \text{as } h, N^{-1}, \tau &\rightarrow 0. \end{aligned} \tag{6.12}$$

Thus, in this case we have (6.11) for  $t_1 = T$ . If  $\sigma \leq \theta/(2\theta - 1)$  and (6.8) is satisfied, in addition, then we have (6.12) also. Hence (6.11) holds for  $t_1 = T$ . Thus we complete the proof of Theorem 1.

REFERENCES

1. J. W. Murdock, *AIAA J.* **15**, 1167 (1977).
2. J. W. Murdock, AIAA Paper 86-0434, Washington, DC, 1986 (unpublished).
3. D. B. Ingham, *J. Comput. Phys.* **53**, 90 (1984).
4. D. B. Ingham, *Proc. R. Soc. London A* **402**, 109 (1985).
5. S. Beringen, *J. Fluid Mech.* **148**, 413 (1984).
6. F. A. Milinazo, and P. G. Saffman, *J. Fluid Mech.* **160**, 281 (1985).
7. B.-Y. Guo, *J. Comput. Math.* **6**, 238 (1988).
8. C. Canuto, Y. Maday, and A. Quarteroni, *Numer. Math.* **39**, 205 (1982).
9. C. Canuto, Y. Maday, and A. Quarteroni, *Numer. Math.* **44**, 201 (1984).
10. B.-Y. Guo and W.-M. Cao, *Acta Math. Appl. Sin.* **7**, 1 (1991).
11. S. A. Orszag, *J. Fluid Mech.* **49**, 75 (1971).
12. S. A. Orszag and L. C. Kells, *J. Fluid Mech.* **96**, 159 (1980).
13. B. L. Rozhdestvensky and I. N. Simakin, *J. Fluid Mech.* **147**, 261 (1984).
14. R. Témán, *Navier-Stokes Equations* (North-Holland, Amsterdam, 1977).
15. L. Ying, *Adv. in Math.* **12**, 124 (1983).
16. J. T. Oden, "RIP—Methods for Stokesian Flows," *Finite Element Methods in Fluids*, edited by R. H. Gallagher *et al.* (Wiley, New York, 1982).
17. P. Grisvard, *Ann. Sci. Ecole Norm. Sup.* **4**, 311 (1969).
18. P. G. Ciarlet, *The Finite Element Method for Elliptic Problems* (North-Holland, Amsterdam, 1978).
19. B.-Y. Guo, *Difference Methods for Partial Differential Equations* (Science Press, Beijing, 1988).